

## Appendix B

### Proof of a Geometric Relationship

The purpose of this Appendix is to prove a differential relationship central to the derivation of the integral kernel for incident angular fluxes. We begin with the local coordinate system illustrated in Fig. 1. We define  $s_b(\vec{\Omega})$  to be the distance to the outer boundary from the point  $\vec{r}$  along the direction,  $-\vec{\Omega}$ . For each direction,  $\vec{\Omega}$ , the vector  $\vec{r}_b$ , where

$$\vec{r}_b = \vec{r} - s_b \vec{\Omega} . \quad (1)$$

represents a point on the outer surface of the transport domain. Assuming a non-reentrant transport domain, each point on the outer surface corresponds to a unique value of  $\vec{\Omega}$ , and each value of  $\vec{\Omega}$  corresponds to a unique point on the outer surface. It follows from basic principles of calculus that

$$dA = \left\| \frac{\partial \vec{r}_b}{\partial \mu} \times \frac{\partial \vec{r}_b}{\partial \Phi} \right\| d\mu d\Phi , \quad (2)$$

where  $dA$  is the differential surface area associated with the surface point  $\vec{r}_b$ ,  $\vec{\Omega}$  is defined by the polar and azimuthal angles,  $\theta$  and  $\Phi$ , respectively, and  $d\mu d\Phi = d\Omega$ , where  $\mu = \cos \theta$ .

The outward-directed surface normal at point  $\vec{r}_b$  is given by

$$\vec{n} = \left( \frac{\partial \vec{r}_b}{\partial \mu} \times \frac{\partial \vec{r}_b}{\partial \Phi} \right) / \left\| \frac{\partial \vec{r}_b}{\partial \mu} \times \frac{\partial \vec{r}_b}{\partial \Phi} \right\| . \quad (3)$$

Thus, using Eqs. (2) and (3), we find that

$$\left| \vec{\Omega} \cdot \vec{n} \right| dA = \left| \vec{\Omega} \cdot \left( \frac{\partial \vec{r}_b}{\partial \mu} \times \frac{\partial \vec{r}_b}{\partial \Phi} \right) \right| d\mu d\Phi. \quad (4)$$

From Eq. (1), it follows that

$$\frac{\partial \vec{r}_b}{\partial \mu} = - \left( \frac{\partial s_b}{\partial \mu} \vec{\Omega} + s_b \frac{\partial \vec{\Omega}}{\partial \mu} \right), \quad (5a)$$

and that

$$\frac{\partial \vec{r}_b}{\partial \mu} = - \left( \frac{\partial s_b}{\partial \Phi} \vec{\Omega} + s_b \frac{\partial \vec{\Omega}}{\partial \Phi} \right). \quad (5b)$$

Thus,

$$\begin{aligned} \frac{\partial \vec{r}_b}{\partial \mu} \times \frac{\partial \vec{r}_b}{\partial \Phi} &= \frac{\partial s_b}{\partial \mu} \frac{\partial s_b}{\partial \Phi} (\vec{\Omega} \times \vec{\Omega}) + \frac{\partial s_b}{\partial \mu} s_b \left( \vec{\Omega} \times \frac{\partial \vec{\Omega}}{\partial \Phi} \right) + \\ &\quad s_b \frac{\partial s_b}{\partial \Phi} \left( \frac{\partial \vec{\Omega}}{\partial \mu} \times \vec{\Omega} \right) + s_b^2 \left( \frac{\partial \vec{\Omega}}{\partial \mu} \times \frac{\partial \vec{\Omega}}{\partial \Phi} \right). \end{aligned} \quad (6)$$

The first term on the right side of Eq. (6) is identically zero, and the second and third terms are orthogonal to  $\vec{\Omega}$ . Thus

$$\vec{\Omega} \cdot \left( \frac{\partial \vec{r}_b}{\partial \mu} \times \frac{\partial \vec{r}_b}{\partial \Phi} \right) = s_b^2 \vec{\Omega} \cdot \left( \frac{\partial \vec{\Omega}}{\partial \mu} \times \frac{\partial \vec{\Omega}}{\partial \Phi} \right). \quad (7)$$

One finds by direct evaluation that

$$\left( \frac{\partial \vec{\Omega}}{\partial \mu} \times \frac{\partial \vec{\Omega}}{\partial \Phi} \right) = -\vec{\Omega}. \quad (8)$$

Substituting from Eq. (8) into Eq. (7), we find that

$$\vec{\Omega} \cdot \left( \frac{\partial \vec{r}_b}{\partial \mu} \times \frac{\partial \vec{r}_b}{\partial \Phi} \right) = -s_b^2. \quad (9)$$

Finally, substituting from Eq. (9) into Eq. (4), we obtain the desired geometric relationship:

$$\begin{aligned} \left| \vec{\Omega} \cdot \vec{n} \right| dA &= s_b^2 d\mu d\Phi, \\ &= s_b^2 d\Omega. \end{aligned} \tag{10}$$

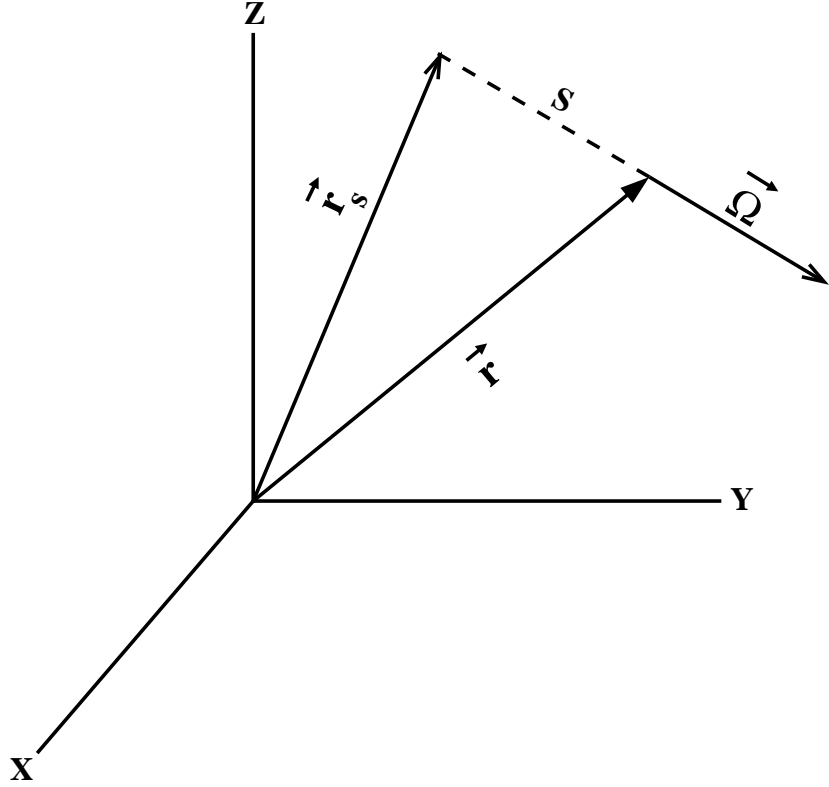


Figure 1: The local spatial coordinate system at the point  $\vec{r}$ . Note that  $\vec{r}_s = \vec{r} - s\vec{\Omega}$ . This is a form of local spherical coordinate system with  $\vec{\Omega}$  playing the role of both a spatial and angular variable.